



# Non-Destructive Testing for Concrete Bridge Decks (R06A)

## California Department of Transportation

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*Peer Exchange*  
*January 30-31 2019*



U.S. Department of Transportation  
Federal Highway Administration

AMERICAN ASSOCIATION  
OF STATE HIGHWAY AND  
TRANSPORTATION OFFICIALS

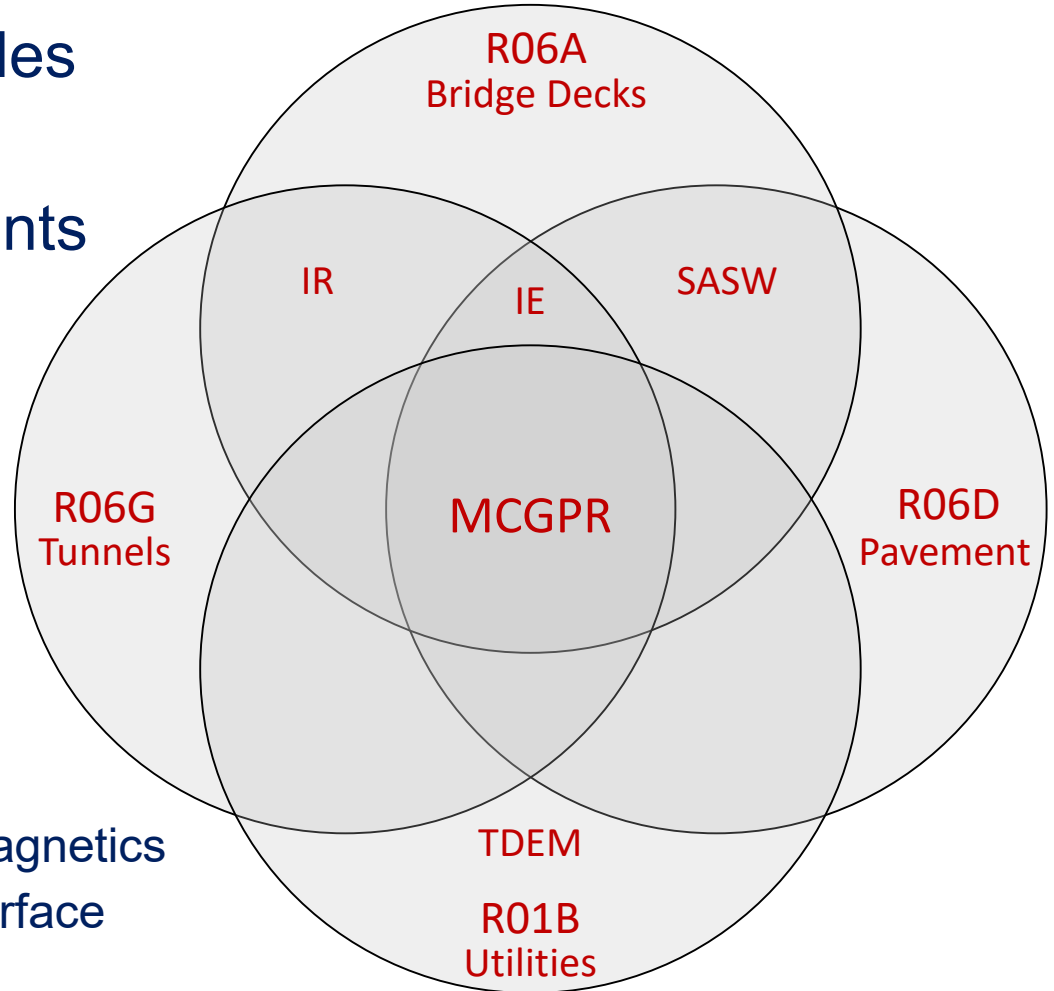
**AASHTO**

# History of GPR at Caltrans

- 1998: PE IV and PE 1000
  - Utilities, NDT, Geotech
- 2000: Tow Cart
  - Pavements
- 2001: 2-½ D Applications
  - Void mapping
  - Pavement research
- 2006: 3-D Visualization
- 2008: Upgrades (PE Pro)
  - Improved tow cart, larger grids, high sample density
- 2009: Pavement Management
  - 58,000 Lane Miles (2009-2012)
- 2011: Subsurface Utility Engineering (SUE)
- 2015: Multichannel Radar
  - Product Demos (IDS, 3D Radar)
  - Bridge Deck Pilot (3D Radar)
  - SHRP2 Round 6 (R01B-SUE)
- 2016: SHRP2 Round 7
  - R06D (Pavement)
  - R06A/G (Bridge decks/Tunnels)
  - R01B (SUE)

# SHRP2 Technology Overlap

- No single grant provides full funding
- Leverage multiple grants for technology acquisition



IE – Impact Echo

IR – Infrared (Thermal Imaging)

TDEM – Time Domain Electromagnetics

SASW – Spectral Analysis of Surface Waves

MCGPR – Multichannel GPR

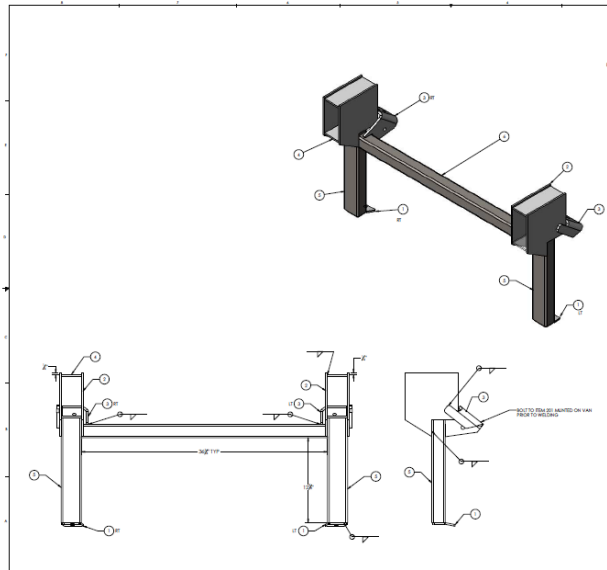
# Caltrans SHRP2 Goals

- Validate GPR technology for diverse applications
- Bring high-speed GPR technology to Caltrans for bridge decks & pavements
- Improve testing methodology and reporting
- Training and technology transfer
- Develop appropriate roles, responsibilities and business practices for collaboration

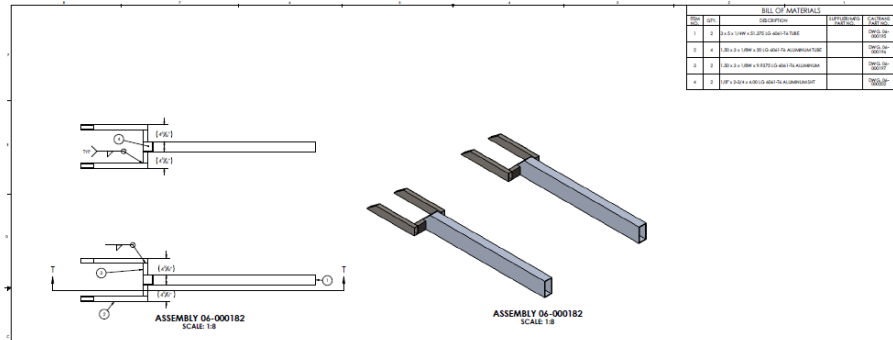
# 3D Radar Implementation

- Collaboration at State & National Level
  - Funding through FHWA & AASHTO
  - Design and Fabrication through CT-GS and CT-DOE
  - Installation and Testing through CT-GS and UC Davis
- Implementation Challenges
  - Short Delivery Schedule
  - Rigid Mounting System
  - Reliable Power Supply
  - I/O From Multiple Data Streams

# Mounting System Fabrication



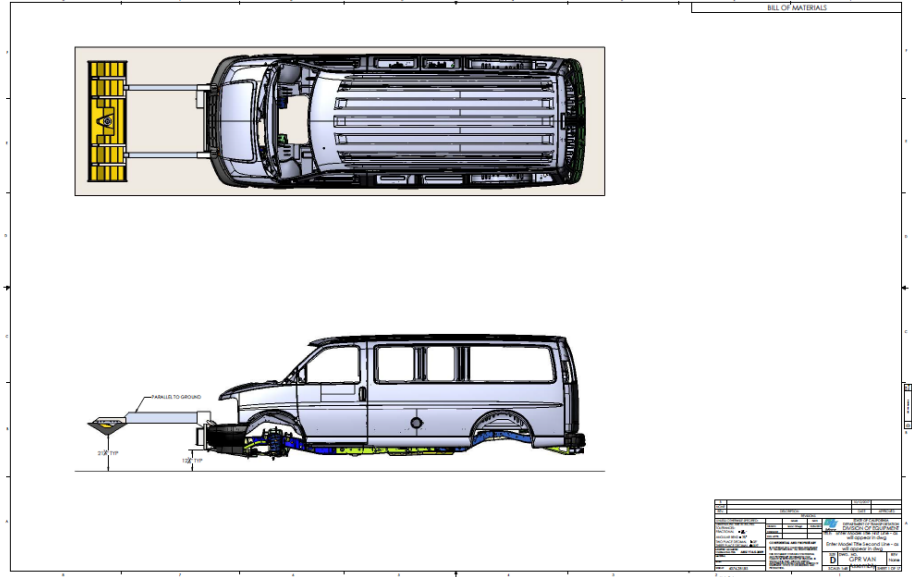
| BILL OF MATERIALS |     |                      |          |
|-------------------|-----|----------------------|----------|
| ITEM              | QTY | DESCRIPTION          | REVISION |
| 1                 | 1   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 2                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 3                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 4                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 5                 | 1   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 6                 | 1   | 2x2x1/8 ALUMINUM TUB | 000001   |



| BILL OF MATERIALS |     |                      |          |
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| 4                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |

## • Critical Design Criteria

- 48" Antenna/Vehicle Separation
- <24" Antenna Height
- Use All Four Mounting Brackets



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| ITEM              | QTY | DESCRIPTION          | REVISION |
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| 3                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |
| 4                 | 4   | 2x2x1/8 ALUMINUM TUB | 000001   |

# Final Assembly

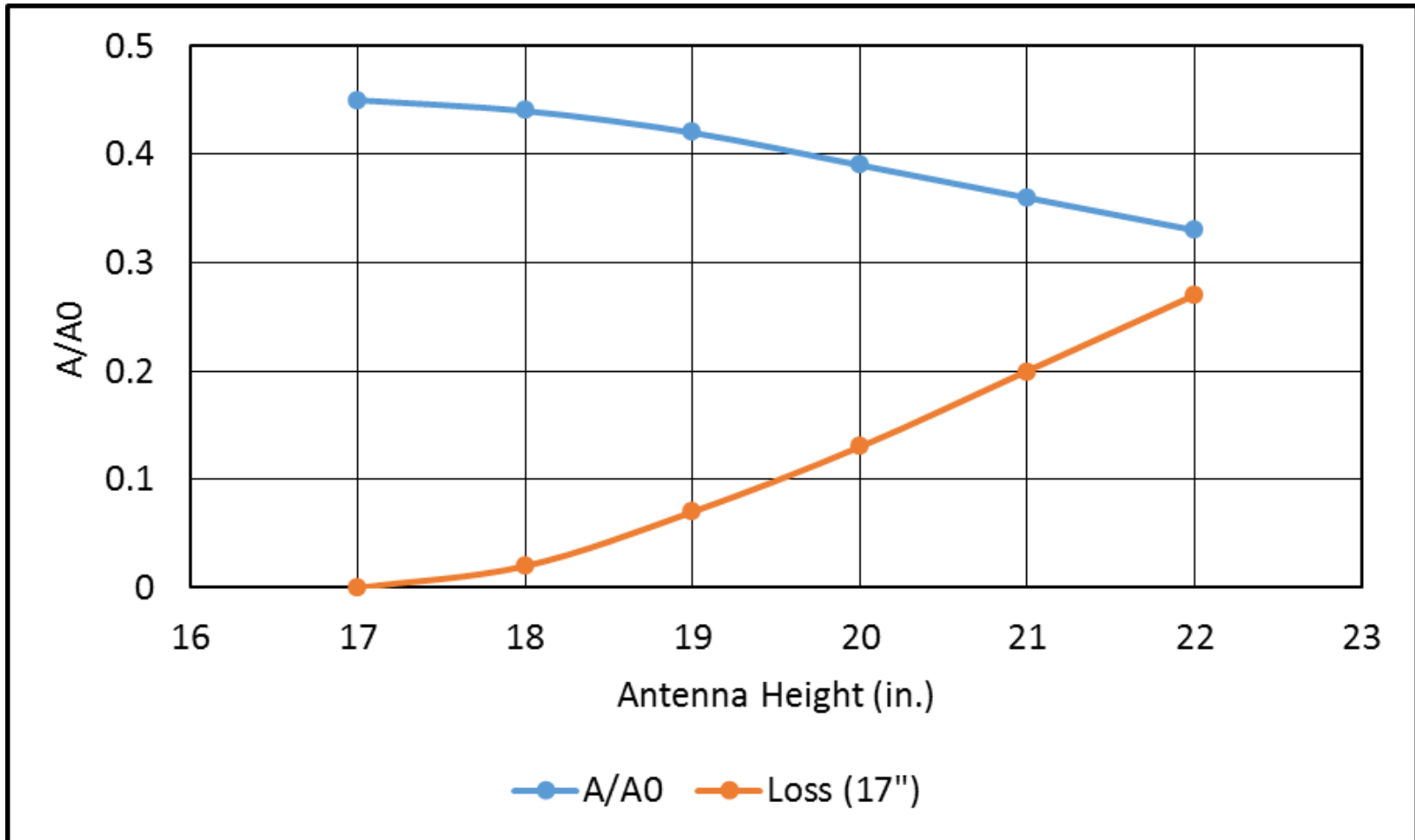


# Final Assembly, Interior





# Energy Loss vs. Antenna Height



# POS LV - GNSS Aided Inertial Navigation

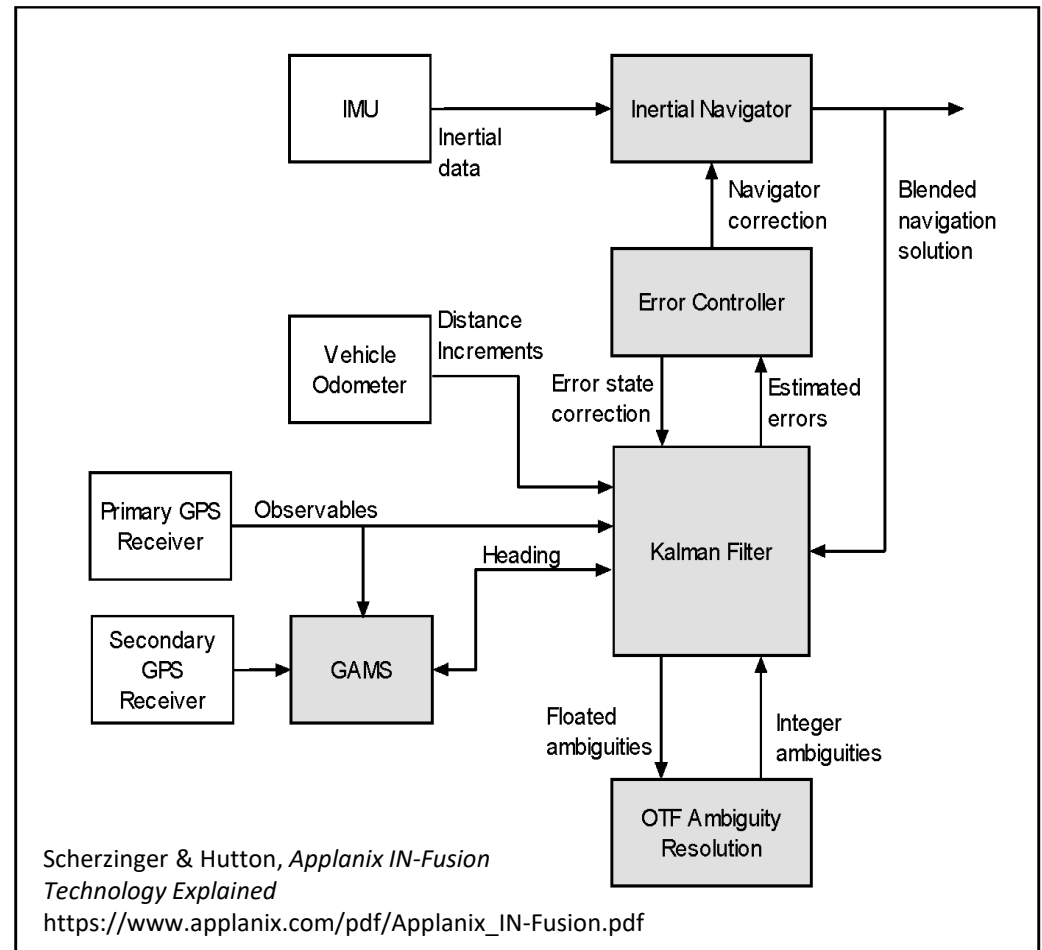
- Dual Antenna GNSS
  - ✓ position, attitude & heading
- Three-axis IMU
  - ✓ Accelerometer & gyroscope
  - ✓ 100 Hz output
- DMI Odometer
  - ✓ Up to 20,000 pulse/m
- Integrated processor
- PC interface
  - ✓ Real-time output
  - ✓ User parameter controls



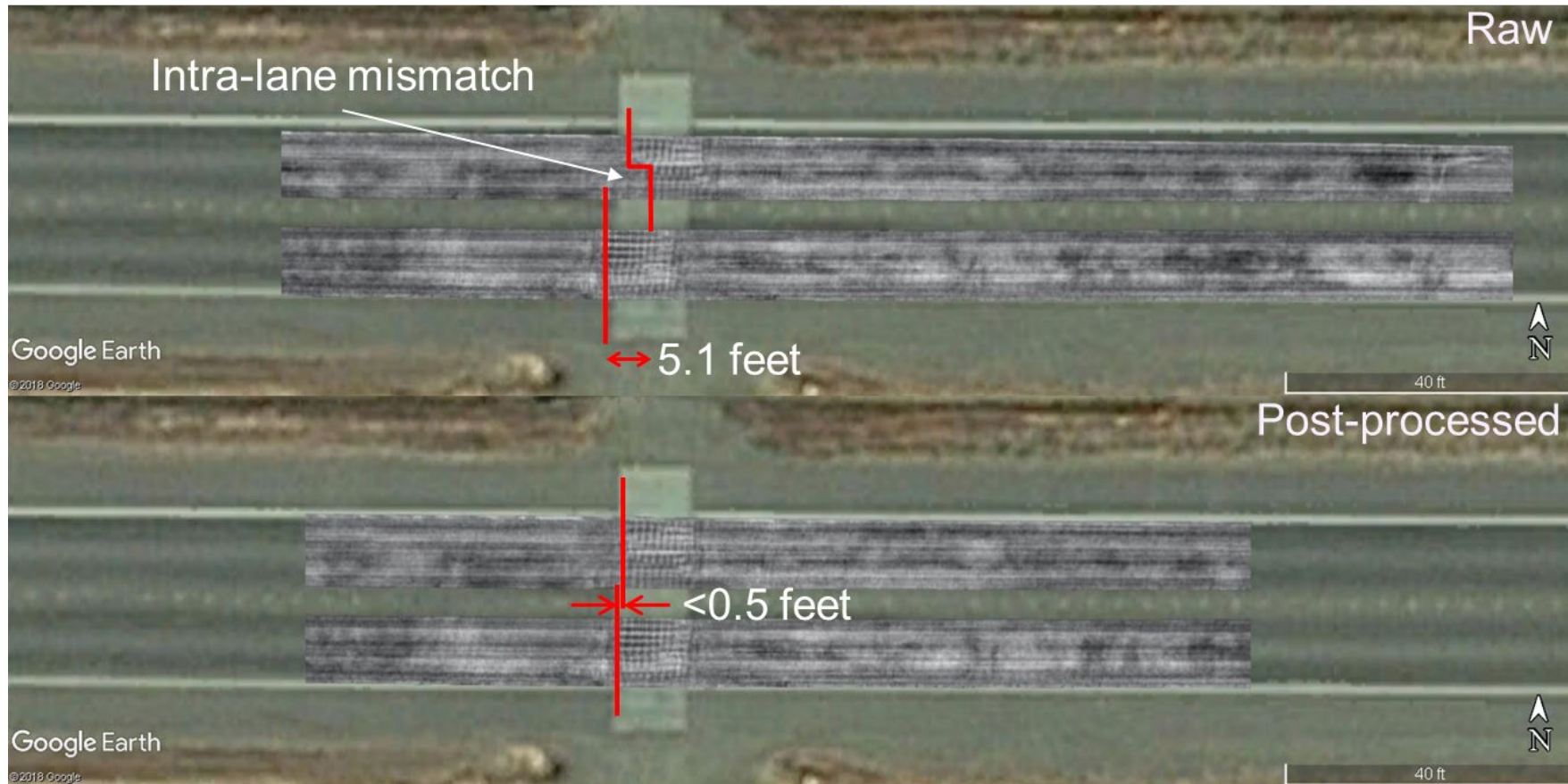
[https://www.applanix.com/img/gallery/pos\\_lv\\_imu\\_ant\\_dmi.png](https://www.applanix.com/img/gallery/pos_lv_imu_ant_dmi.png)

# Real-Time Onboard Processing

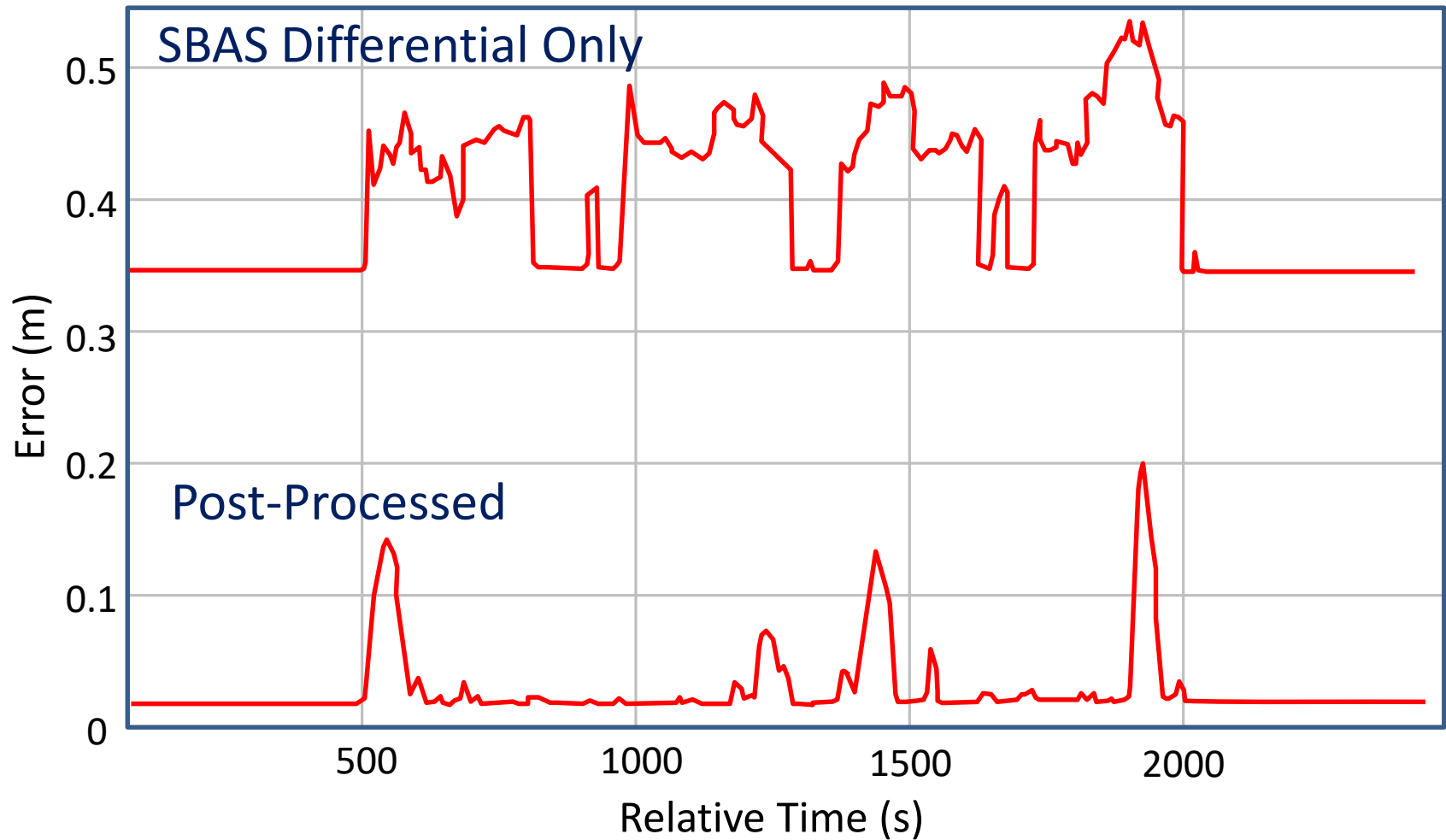
- Kalman filter -- raw pseudorange & carrier phase
- IMU -- resolution of initial ambiguities, maintains accuracy during “cycle slip” or GNSS outage (solution from last known position)
- GNSS Azimuth Measurement Subsystem (GAMS) -- heading & attitude
- Distance Measurement indicator (DMI) -- constrains velocity error and IMU drift



# Examiner Image Correction, 50 MPH



# GNSS Post-Processing



# Examiner Image Quality vs. Position Sample Output



# Types of Outputs

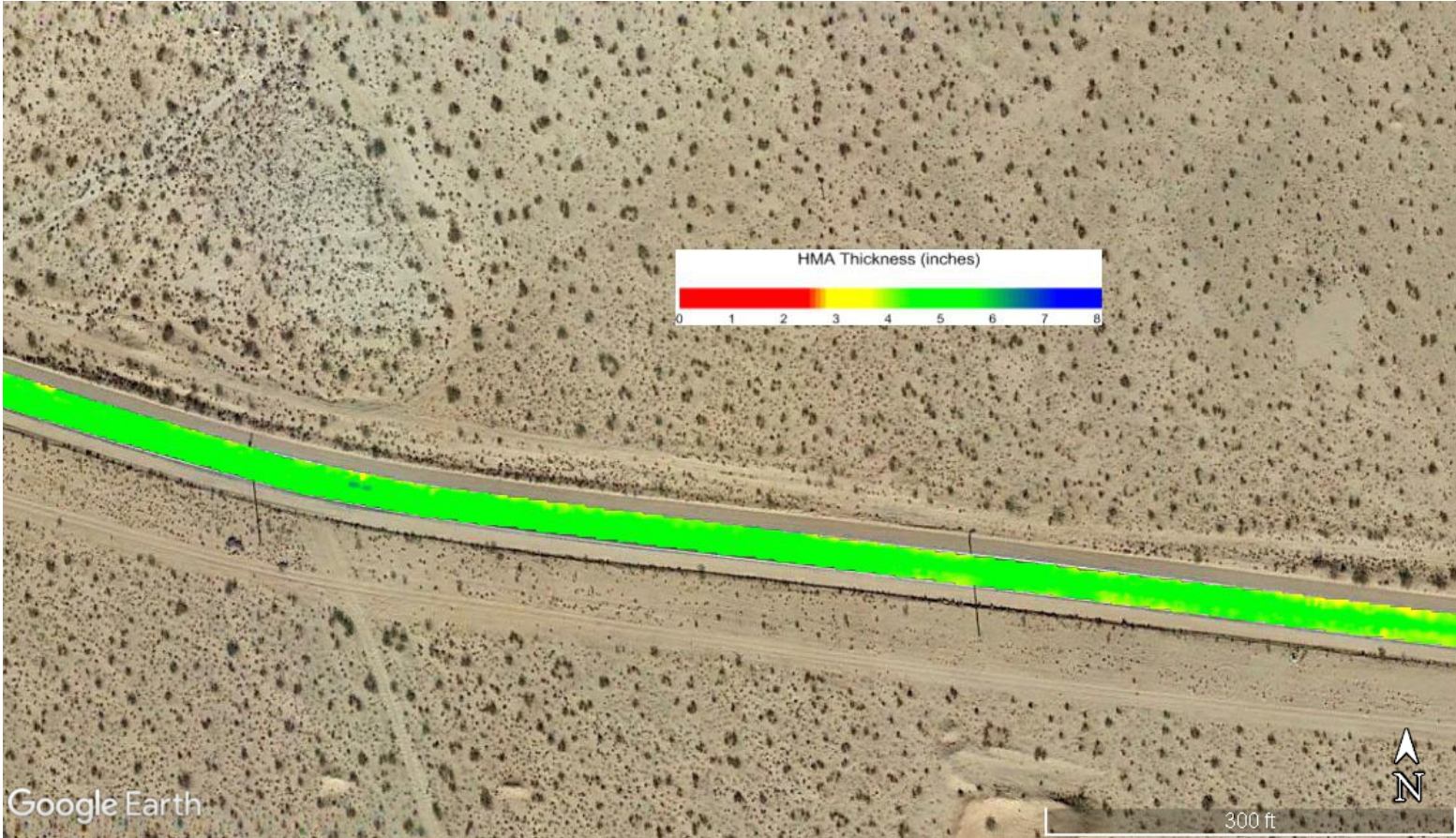
## Analysis Outputs

- Total pavement thickness
- Intra-layer (Overlay) thickness
- Overlay delamination
- Void distribution
- Rebar location
- Concrete degradation
- Subsurface utility location

## QC Outputs

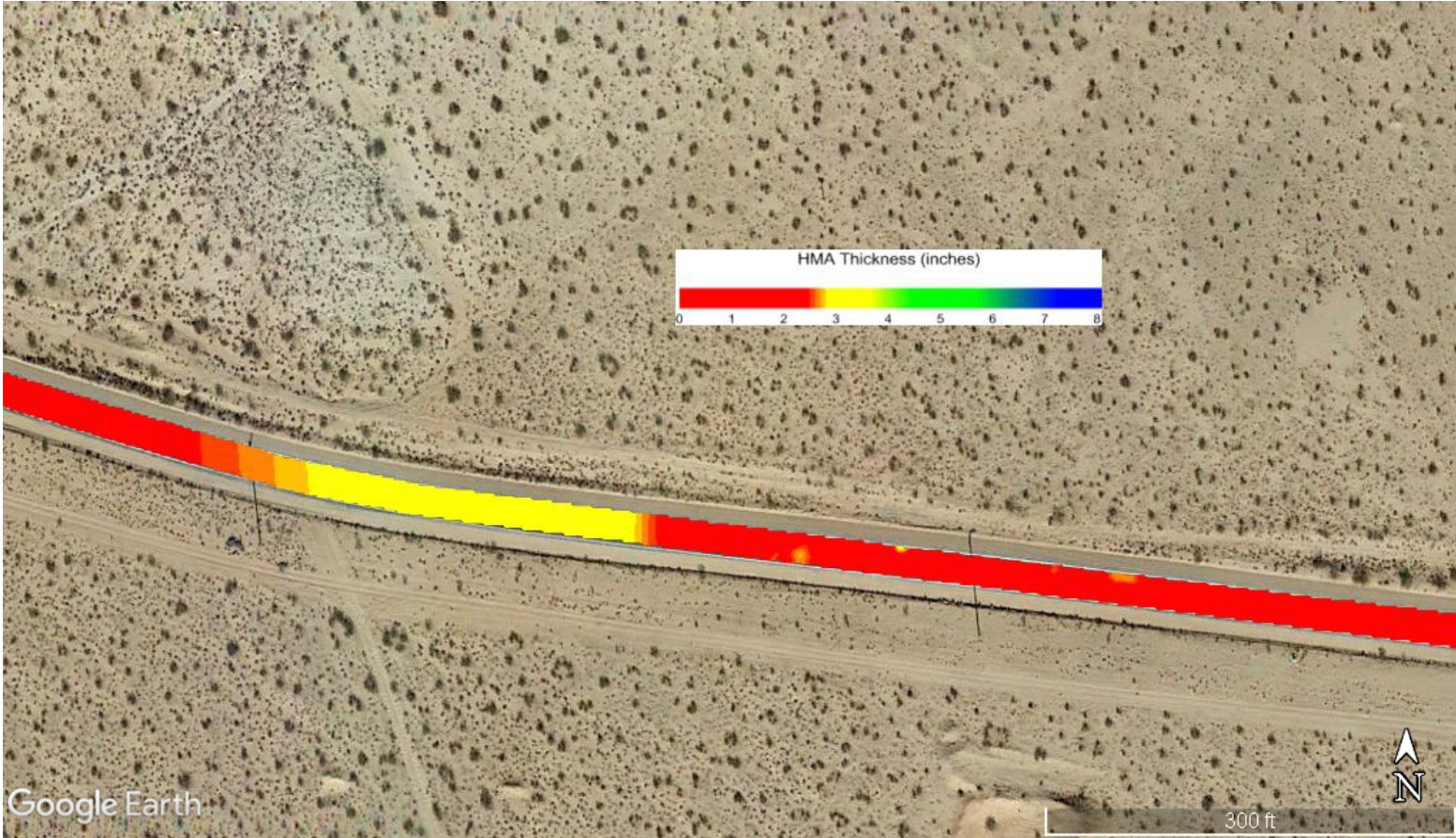
- Gridding accuracy
- Intra-layer accuracy
- Georeferencing accuracy
- Depth/thickness correlation

# SR 247, Total HMA Thickness

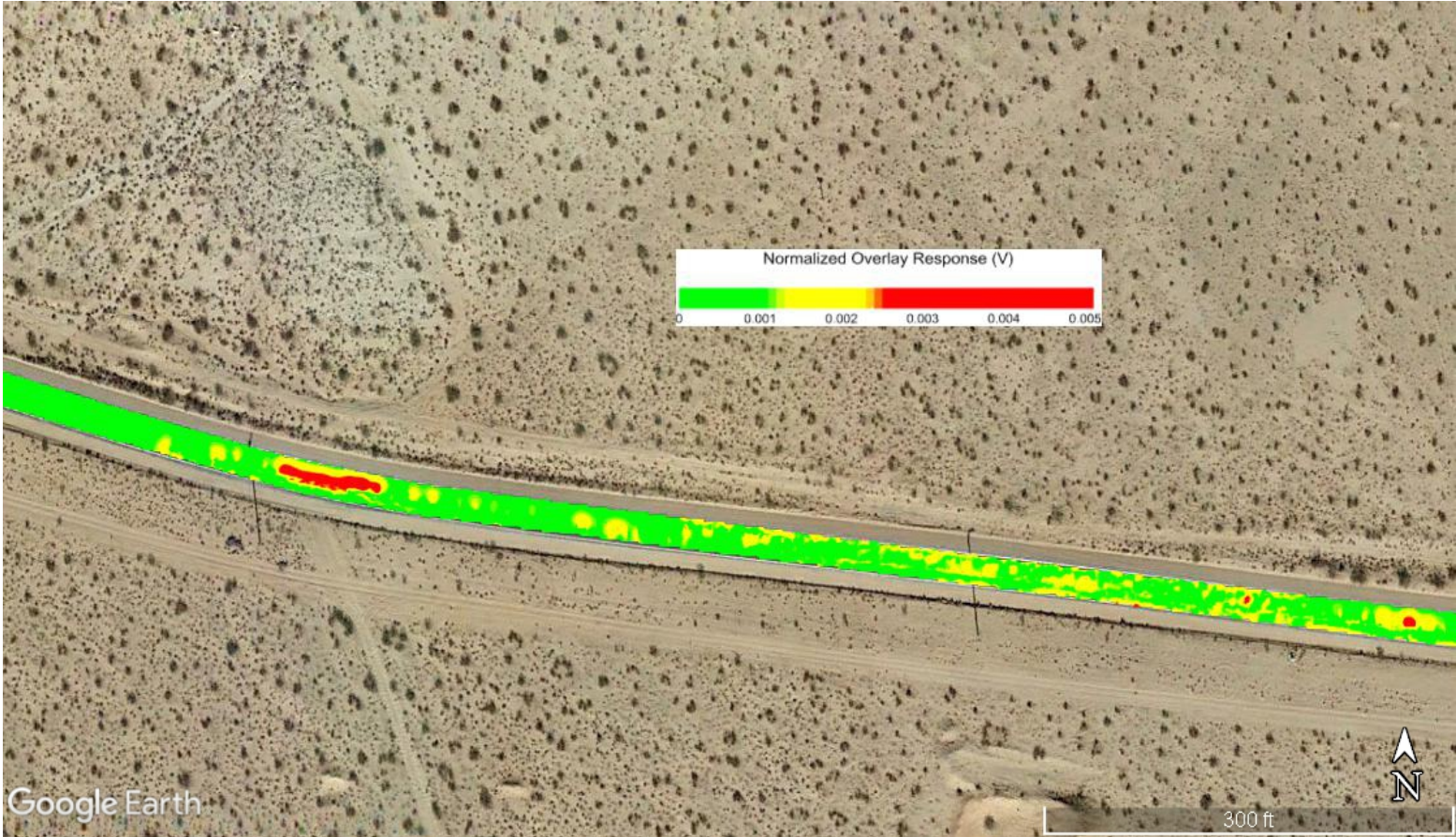




# SR 247, Overlay Thickness



# SR 247, Overlay Response



# Going Forward

- Process Improvement
  - ✓ QA/QC
  - ✓ Automation of data processing/analysis
- Integration with optical and thermal imaging systems
  - ✓ Camera delivery February 2019
  - ✓ Full synthesis with existing systems
  - ✓ Additional state research funding for implementation
- Deployment for bridge deck surveys Spring 2019



# Acknowledgements

- FHWA/AASHTO
- University of California, Davis
  - ✓ Advanced Highway Materials Research Center
- 3D Radar
- Applanix
- California Department of Transportation
  - ✓ Division of Equipment
  - ✓ Office of Land Surveys
  - ✓ Pavement Program
  - ✓ Geophysics and Geology Branch